



UNIVERSITY OF
LINCOLN

Protocols for geometry and cell optimization



Matt Watkins
mwatkins@lincoln.ac.uk

Optimization

- Optimize what? Positions of the atoms
 - typically the total energy of the system (potential energy + electron kinetic energy for DFT) at 0K
 - Free energy of the system at finite temperature
- PES – Born-Oppenheimer approximation
- Global vs local?

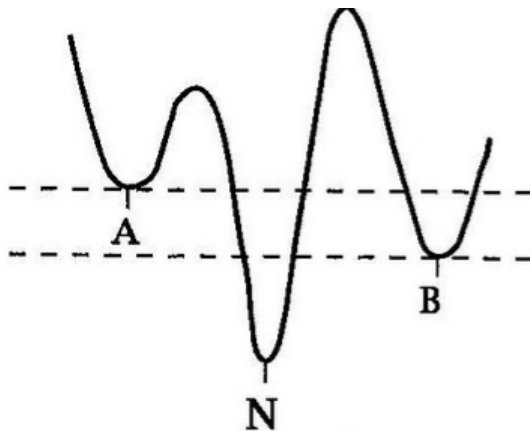


Fig. 3. Defining thermodynamic vs. kinetic reaction coordinates. Which state, A or B, is further "along the reaction coordinate" toward the native state N? State B is *energetically* closer to N (lower energy), but A is *kinetically* closer (smaller barrier to cross).

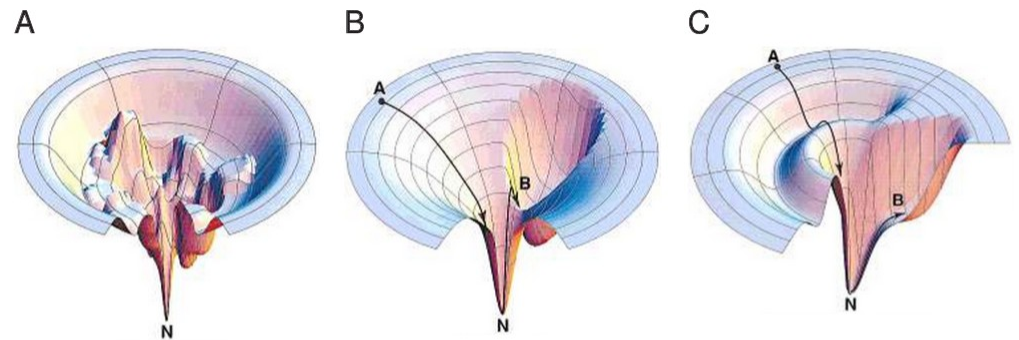


Fig. 12. Different folding scenarios. The vertical axis is internal free energy. Each conformation is represented as a point on the landscape. The two horizontal axes represent the many chain degrees of freedom. **a:** A rugged landscape with hills and traps, folding kinetics is likely multiple-exponential (from Ref. 8). **b:** A landscape in which folding is faster than unfolding. A is a through-

way folding path, whereas unfolding chains (path B) must surmount a barrier to reach the most stable denatured conformations. **c:** A landscape in which folding is slower than unfolding. Most folding paths (path A) pass through a kinetic trap, whereas some low-lying denatured conformations are readily accessible from the native state during unfolding (path B).

Local minimizers

- BFGS
 - most efficient for small–medium size systems with a reasonable guess at the geometry
 - requires inversion/diagonalization of approximate Hessian matrix – Hessian matrix has dimension $3N$ where N is number of atoms being optimized
- L-BFGS
 - is a linear scaling version of the BFGS algorithm (Byrd, Richard H., et al. "A limited memory algorithm for bound constrained optimization. *SIAM Journal on Scientific Computing* 16.5 (1995): 1190-1208.")
- Conjugate gradients
 - Only uses gradients rather than approximation to curvature, should be more robust when far from minima
- Steepest descents
 - head downhill, line search to find how far – most robust far from minima

Global optimizers

- Brute force requires m^{3N} energy evaluations to get a grid of m points in each dimension
- Exponential growth with system size
- Shape of PES can be exploited to get methods that work in practice for modest size systems
 - Random search – just a script for initial coords
 - Genetic algorithms
 - Simulated annealing – ANNEALING keyword in MD section
 - Monte Carlo
 - Basin hopping
- Swarm methods in CP2K have basin hopping
 - \$CP2K/tests/SWARM – Ole Schutt

- GEO_OPT – energy minimization allowing atomic coordinates to change
- CELL_OPT – allow cell parameters to vary when finding the local energy minima too
- CONSTRAINTS – there may be some variables that we want to fix – cell angles or positions of some atoms
- Collective variables – plot energy as function of some variable – a bond length or angle, for instance – reduce dimensionality

GEO_OPT

- RUN_TYPE GEO_OPT in global section
- OPTIMIZER in MOTION section
 - CG, use with poor initial guesses, noisy forces, rough optimization
 - (L)BFGS, for most QS calculations – consider switching to LBFGS above ~1000 atoms. Look for diagonalization routine timings at end of run to see relative cost
- MAX_ITER number of optimization steps
- CONSTRAINTS in MOTION section
 - &FIXED_ATOMS
 - COMPONENTS_TO_FIX X
 - LIST 1
 - &END
 - &FIXED_ATOMS
 - COMPONENTS_TO_FIX Y
 - LIST 2
 - &END

output

- grep for “Max. grad” in output file to see the progress of the optimization – this gives maximum energy gradient on atoms being optimized
- Below “Convergence check :” there is a summary of the progress. Output is like Gaussian for those familiar – convergence requires Max and RMS step size and Max and RMS gradients to be converged.
- Pressure extra criteria for CELL_OPT
- The convergence criteria can be set in the &MOTION section
- Default Max. grad is equal to 0.025 eV/Å
- Good enough for most purposes

```
ENERGY| Total FORCE_EVAL ( QS ) energy (a.u.): -2314.583506508490700
*****
***** 2PNT LINE SEARCH INFO *****
***
*** DX (EVALUATED)= 0.025697 DX (THRESHOLD)= 0.250000 ***
*** DX (FITTED) = 0.252697 DX (ACCEPTED) = 0.250000 ***
*****
----- Informations at step = 4 ----- SD
Optimization Method = SD
Total Energy = -2314.5828781392
Internal Pressure [bar] = 35379.3762511153
Real energy change = -0.0099708467
Decrease in energy = YES
Used time = 465.309

Convergence check :
Max. step size = 0.1443379699
Conv. limit for step size = 0.0030000000
Convergence in step size = NO
RMS step size = 0.0456435465
Conv. limit for RMS step = 0.0015000000
Convergence in RMS step = NO
Max. gradient = 0.0148361189
Conv. limit for gradients = 0.0004500000
Conv. for gradients = NO
RMS gradient = 0.0046915771
Conv. limit for RMS grad. = 0.0003000000
Conv. for gradients = NO
Pressure Deviation [bar] = 35279.3762511153
Pressure Tolerance [bar] = 100.0000000000
Conv. for PRESSURE = NO
-----
CELL| Volume [angstrom^3]: 5.647 0.000 0.000 |a| = 180.188
CELL| Vector a [angstrom]: 0.000 5.647 0.000 |b| = 5.647
CELL| Vector b [angstrom]: 0.000 0.000 5.647 |c| = 5.647
CELL| Angle (b,c), alpha [degree]: 90.000
```

```
----- Informations at step = 5 ----- CG
Optimization Method = CG
Total Energy = -2314.5861062993
Internal Pressure [bar] = 44.8922780589
Real energy change = -0.0032281601
Decrease in energy = YES
Used time = 484.509

Convergence check :
Max. step size = 0.0000000113
Conv. limit for step size = 0.0030000000
Convergence in step size = YES
RMS step size = 0.0000004766
Conv. limit for RMS step = 0.0015000000
Convergence in RMS step = YES
Max. gradient = 0.0000003312
Conv. limit for gradients = 0.0004500000
Conv. in gradients = YES
RMS gradient = 0.0000001945
Conv. limit for RMS grad. = 0.0003000000
Conv. in RMS gradients = YES
Pressure Deviation [bar] = -55.1077219411
Pressure Tolerance [bar] = 100.0000000000
Conv. for PRESSURE = YES
-----
*****
***** GEOMETRY OPTIMIZATION COMPLETED *****
*****
Reevaluating energy at the minimum
```

CELL_OPT

- Only place CP2K uses symmetry(?)
- Can set cell symmetry types in &CELL section

```
&SUBSYS
&CELL
  ABC 9.167 9.167 11.808
  SYMMETRY ORTHORHOMBIC
  MULTIPLE_UNIT_CELL 2 2 2
&END CELL
&TOPOLOGY
  COORD_FILE_NAME tio2.xyz
  COORD_FILE_FORMAT XYZ
  MULTIPLE_UNIT_CELL 2 2 2
```

- Can place constraints on the cell optimization in the %CELL_OPT section

```
&MOTION
  &CELL_OPT
    KEEP_SYMMETRY .TRUE.
  &END CELL_OPT
&END MOTION

SCALE_FACTOR
  {NREP}
```

– KEEP_ANGLES, KEEP_SYMMETRY

CELL_OPT

- Three algorithms in CP2K (version > 2.4) controlled by TYPE variable in \$CELL_OPT
 - GEO_OPT: Original implementation.
 1. Inner cycle optimize atomic positions
 2. Outer cycle optimize cell vectors
 - DIRECT_CELL_OPT: New implementation from version 2.4 onwards – cell parameters (stresses) go into the optimizer along with atomic coordinates
 - MD: Optimize at finite temperature. Uses MD, so only of use if you have a cheap Hamiltonian
- DIRECT_CELL_OPT should be much more efficient – try for yourself
- Generally best to enforce symmetry / fix angles to start with to minimize number of degrees of freedom.

Transition states

Two methods for transition state

- Nudged Elastic Band method – covered by Teo later
- Dimer method – two images of the system (the dimer) calculate energy / force at each – then rotate to find steepest path up hill and head upwards.
 - Needs guess (vector) at the up-hill direction – can be generated from difference in coordinates between minima and guess at TS
 - No guarantee of converging (to the TS you want)
 - Should be a good method for refining TSs obtained from NEB

Optimizing other things

Gradient free optimization

Powell's Algorithm

https://en.wikipedia.org/wiki/Powell%27s_method”

- BASIS SETS – built in
- Pseudo – built in in ATOM package
- FORCE FIELDS – built in force matching algorithm
 - http://www.cp2k.org/exercises:2015_uzh_molsim:h2o_ff
- Anything – general scheme in `${CP2K_ROOT}/cp2k/tools/scriptmini`